

# Realtime A5/1 Attacks with Precomputation Tables

Martin Novotný, Andy Rupp  
Ruhr University Bochum

## Time-Memory Trade-off Tables

- Original Hellman Approach
- Distinguished points
- TMTO with multiple data
- Rainbow tables
- Thin-rainbow tables

## Architecture of the A5/1 TMTO engine

## Implementation results

# Two extreme approaches

Brute force attack

Check all combinations of a key  $K$  online

- time  $T = N = 2^k$
- memory  $M = 1$

Table lookup

(For a given plaintext  $P$ )

All pairs key-ciphertext  $\{K_i, C_i\}$  precomputed and stored (sorted by  $C$ )

Online phase: Look-up  $C$  in the table (and find  $K$ )

- time  $T = 1$
- memory  $M = N = 2^k$



# Time-Memory Trade-Off (Hellman, 1981)

Compromises the above two extreme approaches

*Precomputation phase:* For a given plaintext  $P$ :

- *precompute* (ideally all) pairs key-ciphertext  $\{K_i, C_i\}$ ;
- *store* only **some** of them in the table.

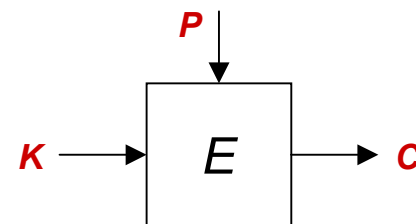
*Online phase:*

- Perform *some* computations;
- lookup the table and find the key  $K$ .
  - time  $T = N^{2/3}$
  - memory  $M = N^{2/3}$

# Precomputation (offline) phase

*Idea:* Encryption function  $E$  is a pseudo-random function

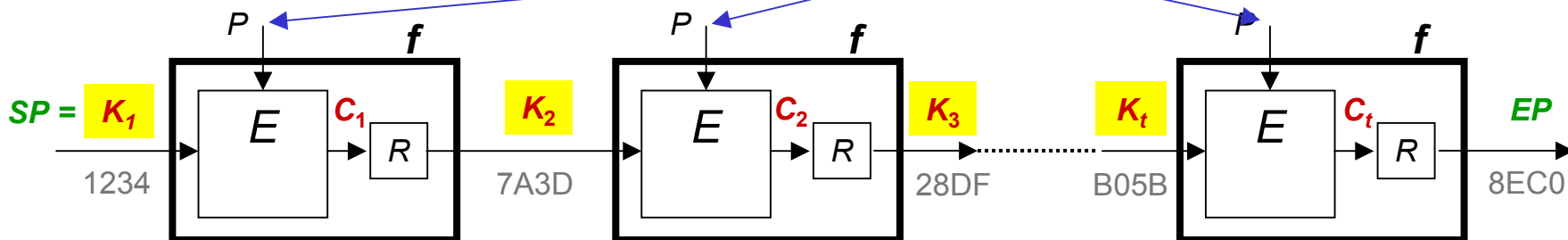
$$C = E_K(P)$$



Pairs  $\{K_i, C_i\}$  organized in chains

- $C_i$  is used to create a key  $K_{i+1}$  for the next step
- $E$  is pseudo-random  $\Rightarrow$  we perform a *pseudo-random walk* in the keyspace

plaintext  $P$  is the same

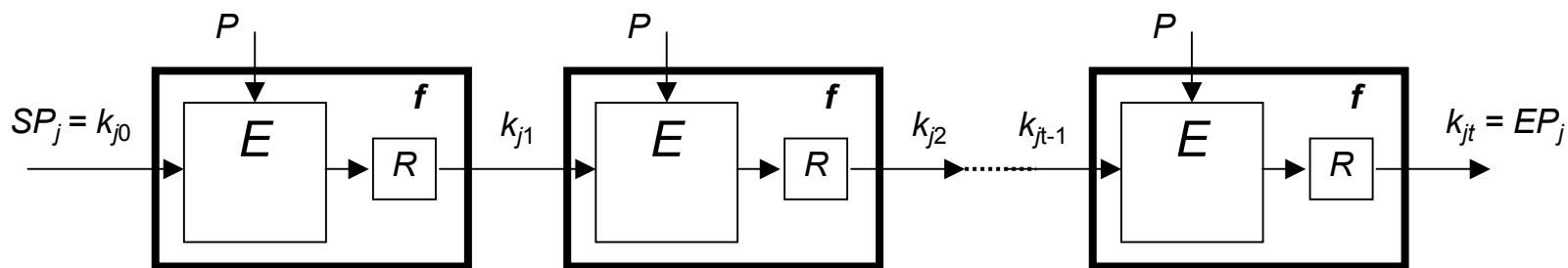


$R$  – reduction function (DES:  $C$  has **64** bits,  $K$  has **56** bits)

$f$  – step function  $f(x) = R(E_x(P))$

## Precomputation (offline) phase

1234  $SP_1 = k_{10} \xrightarrow{f} k_{11} \xrightarrow{f} k_{12} \xrightarrow{f} \dots \xrightarrow{f} k_{1t-1} \xrightarrow{f} k_{1t} = EP_1$  8EC0  
 1235  $SP_2 = k_{20} \xrightarrow{f} k_{21} \xrightarrow{f} k_{22} \xrightarrow{f} \dots \xrightarrow{f} k_{2t-1} \xrightarrow{f} k_{2t} = EP_2$  2A1B  
 1236  $SP_3 = k_{30} \xrightarrow{f} k_{31} \xrightarrow{f} k_{32} \xrightarrow{f} \dots \xrightarrow{f} k_{3t-1} \xrightarrow{f} k_{3t} = EP_3$  4D3C  
 ...  
 9999  $SP_m = k_{m0} \xrightarrow{f} k_{m1} \xrightarrow{f} k_{m2} \xrightarrow{f} \dots \xrightarrow{f} k_{mt-1} \xrightarrow{f} k_{mt} = EP_m$  02E3



$m$  chains with a fixed length  $t$  generated

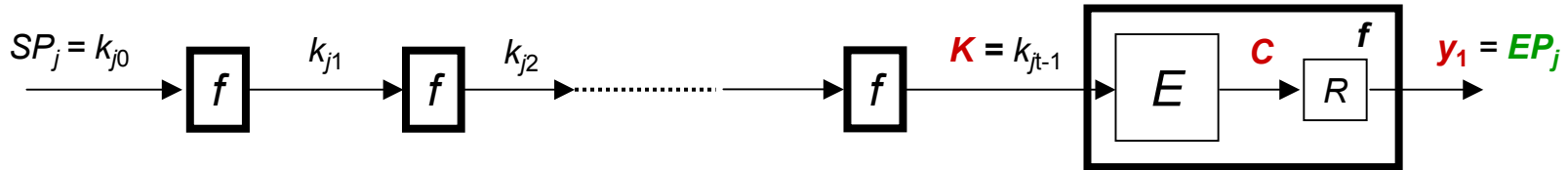
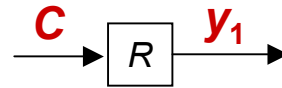


Only pairs  $\{SP_i, EP_i\}$  stored (sorted by  $EP$ )  $\Rightarrow$  reducing memory requirements

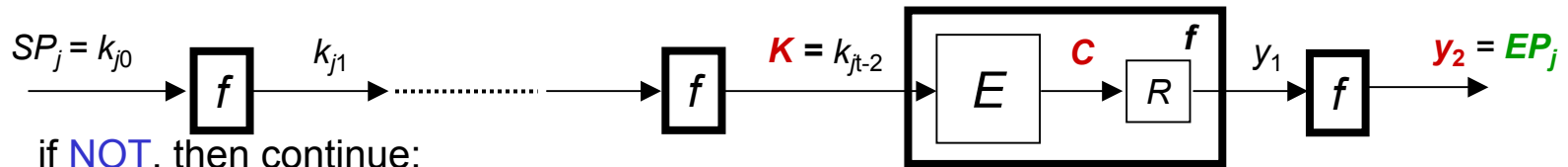
# Online phase

Given  $C$ .

1. Compute  $y_1 = R(C)$ ;  
Lookup table if  $y_1 = EP_j$ 
  1. if YES, then (potentially)  $K = k_{jt-1} \Rightarrow$  compute  $k_{jt-1} = \overbrace{f(f(f(\dots f(SP_j) \dots)))}^{(t-1) \times}$ , stop



2. if NOT, then continue:
2. Compute  $y_2 = f(y_1) = f(R(C))$ ;  
Lookup table if  $y_2 = EP_j$ 
  1. If YES then (potentially)  $K = k_{jt-2} \Rightarrow$  compute  $k_{jt-2} = \overbrace{f(f(f(\dots f(SP_j) \dots)))}^{(t-2) \times}$ , stop



3. Compute  $y_3 = f(y_2) = f(f(y_1)) = f(f(R(C)))$ ;  
Lookup table if  $y_3 = EP_j$

# Birthday paradox problem

$m$  chains of fixed length  $t$  generated

$R$  is not bijective  $\Rightarrow$  some  $k_{ij}$  collide. Collisions yield in chain merges or in cycles in chains

*Matrix stopping rule*: Hellman proved that it is not worth to increase  $m$  or  $t$  beyond the point at which

$$m \cdot t^2 = N$$

(the coverage of keyspace does not increase too much)

He recommends to use  $r$  tables, each with *different* reduction function  $R$

Since also  $N = m \times t \times r$ , then  $r = t$

Hellman recommends  $m = t = r = N^{1/3}$



# Hellman TMTO – Complexity

## Precomputation phase

- Precomputation time  $PT = m \times t \times r = N$
- Memory  $M = m \times r = N^{2/3}$

## Online phase

- Memory  $M = N^{2/3}$
- Online time  $T = t \times r = t^2 = N^{2/3}$
- Table accesses  $TA = T = N^{2/3}$

## Tradeoff curve

$$M^2 T = m^2 t^2 t^2 = m^2 t^4 = N^2$$

$$M^2 T = N^2$$



# Distinguished points

## Precomputation phase

- chains are generated until the *distinguished point* (DP) is reached
  - if the chain exceeds maximum length  $t_{max}$ , then it is discarded and the next chain is generated
  - the chain is also discarded if the DP has been reached, but the chain is too short  $t_{min}$  (to have better coverage)
- triples  $\{SP_j, EP_j, l_j\}$  stored, sorted by  $EP$  ( $l_j$  is a length of the chain)

## Online phase

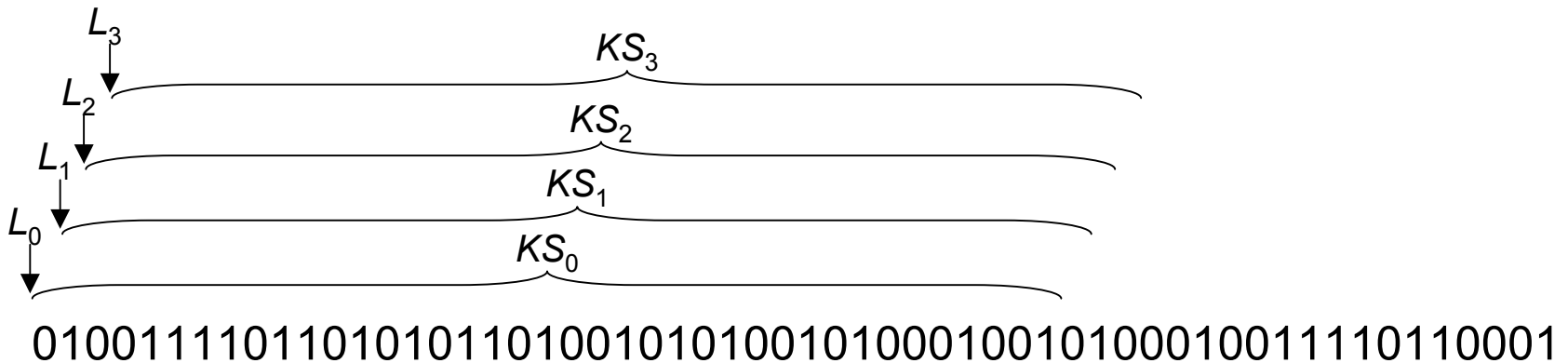
- compute  $y_{i+1} = f(y_i)$  iteratively until the DP is reached (or the maximum length  $t_{max}$  is exceeded)
- lookup the table (only) if the distinguished point is reached

## Advantages

- Table accesses  $TA = r = N^{1/3}$  (c.f.  $TA = t \times r = N^{2/3}$  in original Hellman)
- Chain loops are not possible

# TMTO with multiple data (Biryukov & Shamir, 2000)

Important for stream ciphers: To reveal an internal state  $L_i$  having  $k$  bits we need only  $k$  bits of a keystream  $KS_i$



Having  $D$  data samples of the ciphertext  $C$  (or the keystream  $KS$ ) we have  $D$  times more chances to find the key  $K$  (or the internal state  $L$ )

⇒ We calculate  $r/D$  tables only

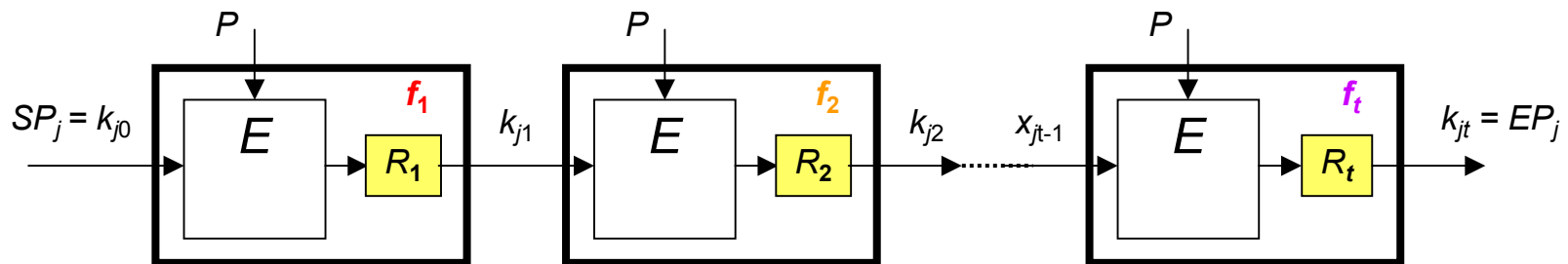
⇒ we save the precomputation time  $PT$  and the memory  $M$

× online time  $T$  and the number of table access  $TA$  remain unchanged

# Rainbow tables (Oechslin, 2003)

*Idea:* to use different reduction function  $R_i$  in each step of chain generation, hence the step functions are:

$f_1 \ f_2 \ f_3 \ \dots \ f_{t-1} \ f_t$



Online phase:

- Compute  $y_1 = R_t(C)$ , compare with  $EPs$ , if no match, then
- Compute  $y_2 = f_t(R_{t-1}(C))$ , compare with  $EPs$ , if no match, then
- Compute  $y_3 = f_t(f_{t-1}(R_{t-2}(C)))$ , compare with  $EPs$ , if no match, then
- ...

# Rainbow tables

Just one table (or only several tables) generated,

- $m = N^{2/3}$  ( $t$  reduction functions used  $\Rightarrow$  the table can be  $t$  times longer),
- $t = N^{1/3}$

## Advantages

- chain loops impossible
- point collisions lead to chain merges only if the equal points appear in the same position of the chain
- online time  $T$  about  $\frac{1}{2}$  of the online time of original Hellman (for single data)
- number of table accesses the same like for the Hellman+DP method (for single data)

## Disadvantages

- Inferior to the Hellman+DP method in the case of multiple data ( $D > 1$ ) (online time  $T$  and the number of table accesses  $TA$  are  $D$ -times greater)

# Thin-rainbow tables

The way to cope with the rainbow tables when having multiple data

The sequence of  $S$  different reduction functions is applied  $k$ -times periodically in order to create a chain:

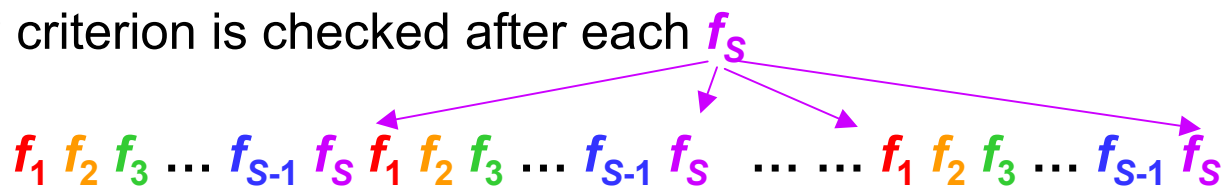
$f_1 f_2 f_3 \dots f_{S-1} f_S f_1 f_2 f_3 \dots f_{S-1} f_S \dots \dots f_1 f_2 f_3 \dots f_{S-1} f_S$

Chain length

$$t = S \times k \quad \Rightarrow \quad S = t/k$$

Thin-rainbow + DP (to reduce # table accesses  $TA$ ):

- DP criterion is checked after each  $f_S$



- We store only chains for which  $k_{min} < k < k_{max}$

# Candidates for implementation (in case of multiple data, $D > 1$ )

1. Hellman + DP
2. Thin-rainbow + DP

Both have the same precomputation complexity

Both have comparable online time  $T$  and # table accesses  $TA$

Hellman+DP checks DP-criterion after **each** step-function  $f$

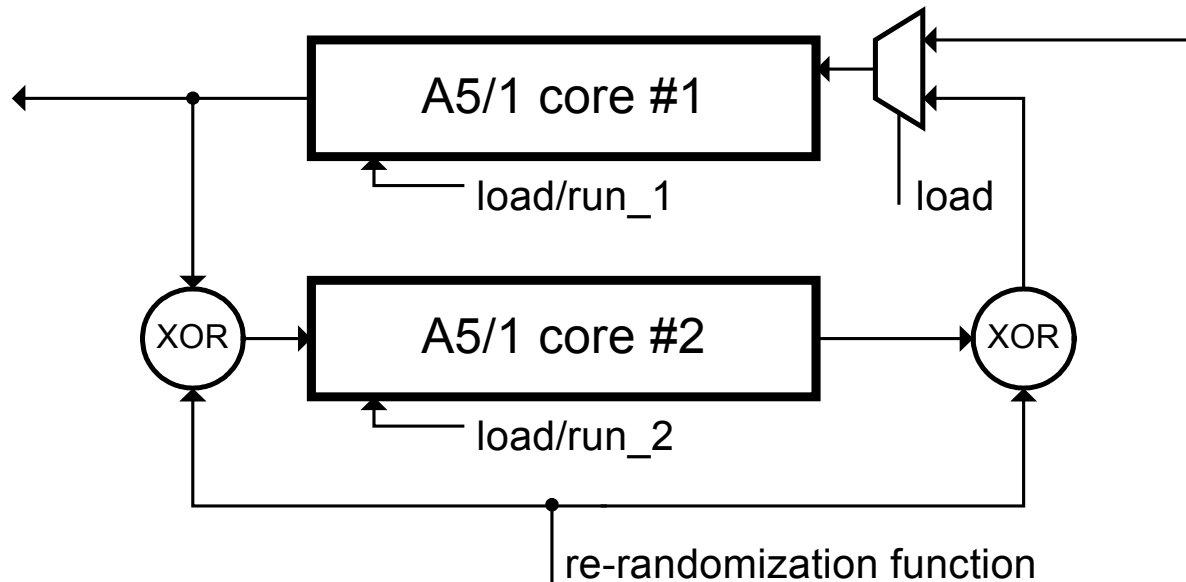
Thin-rainbow+DP checks DP-criterion after  $f_s$  **only**

⇒ We implemented **Thin-rainbow+DP**

- simpler HW, better time/area product
- $S \cong 2^{14}$ ;  $k \cong D \cong 2^6$



# A5/1 TMTO basic element

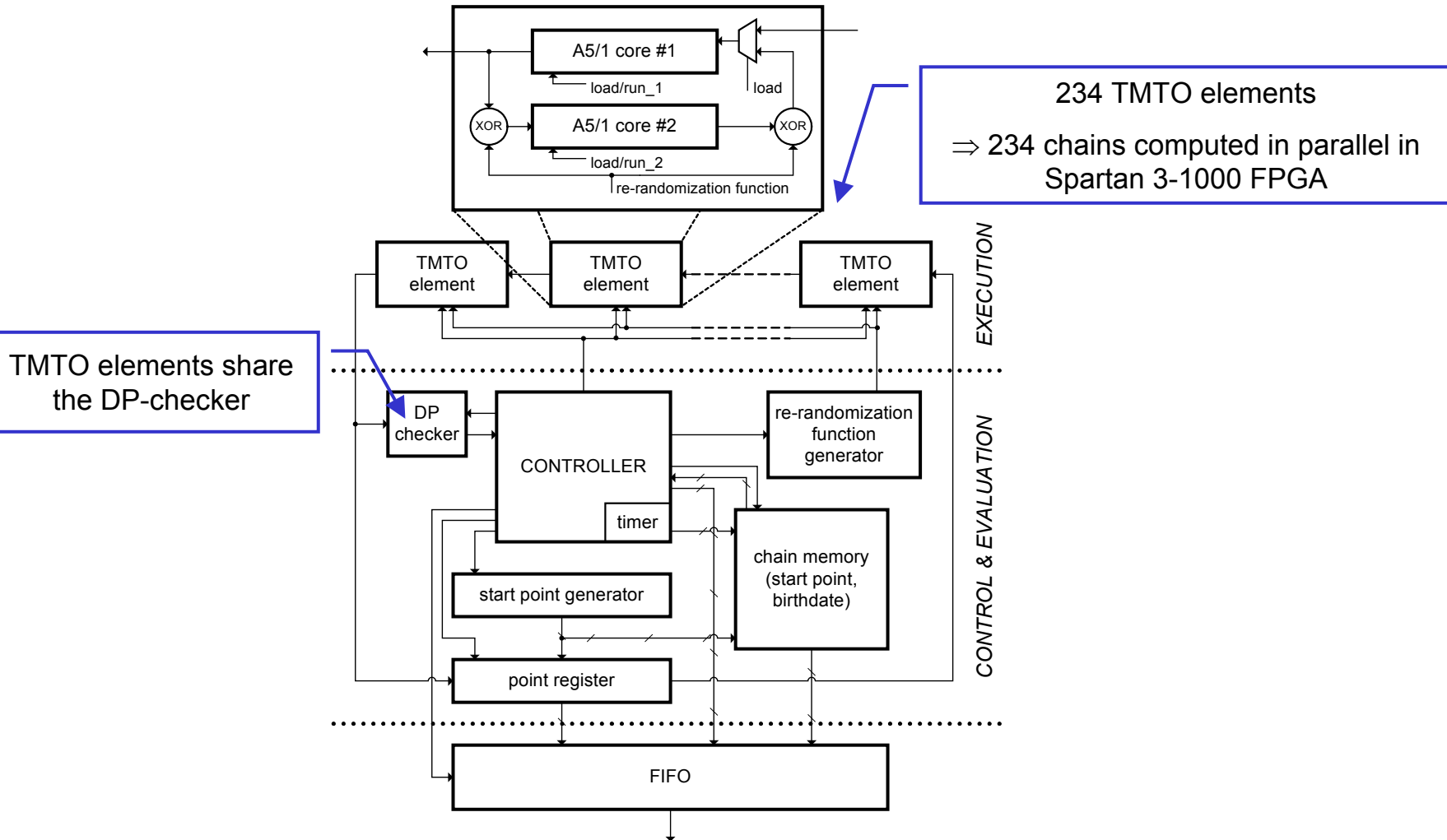


Calculates one chain

Two-stroke mode:

1. core #1 generates keystream, core #2 is loaded
2. core #2 generates keystream, core #1 is loaded

# A5/1 TMTO engine



# Implementation results

COPACOBANA is able to perform up to  $2^{36}$  step-functions  $f_i$  per second

- 234 TMT0 elements/FPGA
- 120 FPGAs
- maximum frequency  $f_{max} = 156$  MHz
- one step-function takes 64 clock cycles

$$234 \times 120 \times 156 \cdot 10^6 / 64 \cong 2^{36}$$

# Parameter choices for $D=64$

chains computed $m$	rainbow sequence $S$	DP criterion $d$ [bits]	#seq. in chain $k$	precomp. time $PT$ [days]	disk usage $DU$ [TB]	online time $OT$ [s]	table accesses $TA$	success ratio $SR$
$2^{41}$	$2^{15}$	5	$[2^3, 2^6]$	337.5	7.49	27.8	$2^{21}$	0.86
$2^{39}$	$2^{15}$	5	$[2^3, 2^7]$	95.4	3.25	36.3	$2^{21}$	0.67
<b><math>2^{40}</math></b>	<b><math>2^{14}</math></b>	<b>5</b>	<b><math>[2^4, 2^7]</math></b>	<b>95.4</b>	<b>4.85</b>	<b>10.9</b>	<b><math>2^{20}</math></b>	<b>0.63</b>
$2^{40}$	$2^{14}$	5	$[2^3, 2^6]$	84.4	7.04	7.0	$2^{20}$	0.60
$2^{39}$	$2^{15}$	5	$[2^3, 2^6]$	84.4	3.48	27.8	$2^{21}$	0.60
$2^{40}$	$2^{14}$	5	$[2^4, 2^6]$	84.4	5.06	8.5	$2^{20}$	0.55
$2^{37}$	$2^{15}$	6	$[2^4, 2^8]$	47.7	0.79	73.5	$2^{21}$	0.42