

The Stochastic Approach in Power Analysis – A Synthesis between Engineer's Expertise and Advanced Stochastics

Werner Schindler

Federal Office for Information Security (BSI), Bonn

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Outline

- dpa
- Template attacks
- The stochastic approach
 - Description and mathematical background
 - Examples and experimental results
 - Comparison with other attacks
 - Advantages and useful properties
- Final Remarks

Preliminary remark

- In this talk we concentrate on power attacks on block ciphers

- Example: AES
 - The key is guessed byte by byte (= 8-bit subkeys)
 - The 16 subkeys are guessed independently.

DPA (Differential Power Analysis)

Pioneer work: Kocher, Jaffe, Jun (1999)

Basic idea: dpa exploits correlations between a function of a subkey (e.g. its Hamming weight) and the electrical current at time t (2nd order dpa: 2 time instants)

- ❑ + preparatory work: moderate
- ❑ - attacking efficiency: moderate

Disadvantages / Problems:

- ❑ Usually dpa only exploits a small fraction of the available information.
- ❑ It is not clear how to combine information from different time instants.

Template attacks (I)

Pionier work: Chari, Rao, Rohatgi (2002)

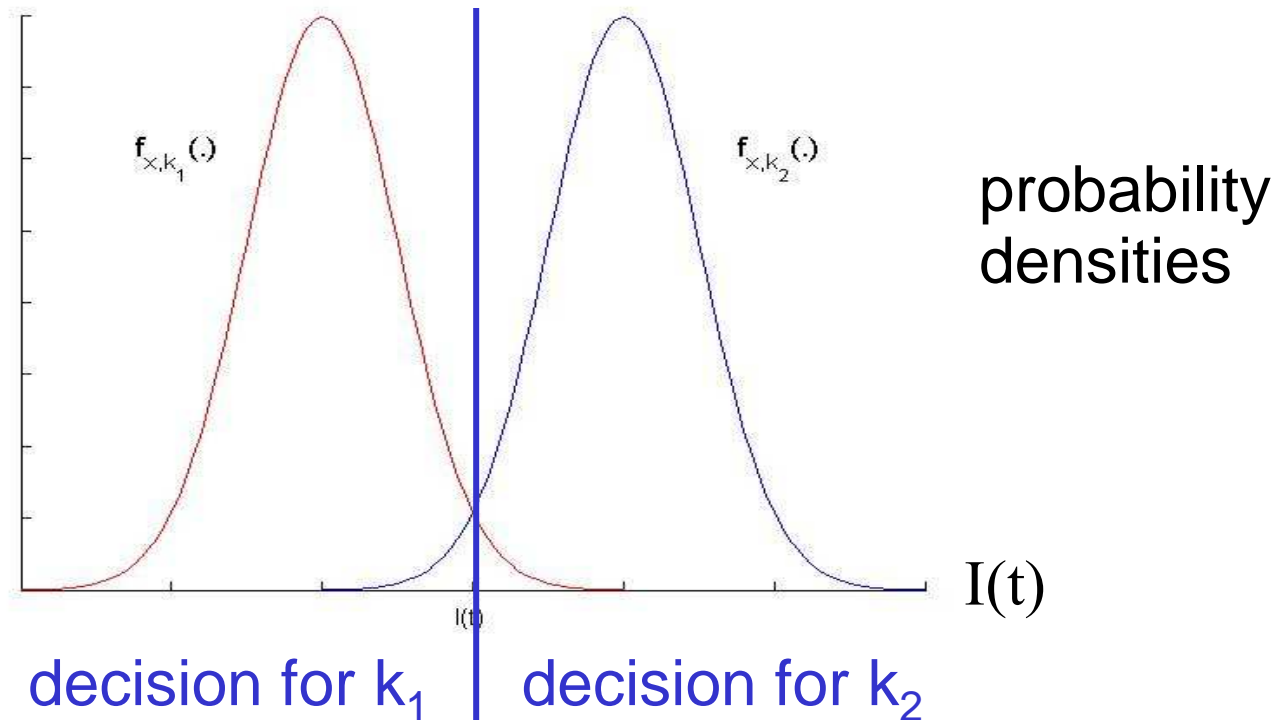
Basic idea:

- For each plaintext byte x , each subkey k , (possibly for each masking value z) the measurement values (\sim electrical current) at time instants $t_1 < \dots < t_m$ are interpreted as values that are assumed by random variables $I_{t_1}(x,k), \dots, I_{t_m}(x,k)$, resp. of $I_{t_1}(x,z,k), \dots, I_{t_m}(x,z,k)$.
- The distributions of these random variables are unknown.
- Profiling: Estimates for the probability densities (for all pairs (x,k) , resp. for all triplets (x,z,k)) are gained from measurements performed at an identical training device.

Template attacks (II)

Attack: Measurement values from the target device are substituted into the estimated densities (\rightarrow maximum likelihood estimator)

Example: $m=1$



Template attacks (III)

Advantages / disadvantages

- + attacking efficiency: maximal (for given $t_1 < \dots < t_m$)
- - profiling workload: gigantic, especially for strong implementations and in case of masking
- - A successful template attack shows that the implementation is vulnerable but does not identify the weakness

The stochastic approach (I)

- Theoretical foundations:
Schindler, Lemke, Paar (2005), Schindler (2008)
- Experimental work:
Schindler, Lemke, Paar (2005), Gierlichs, Lemke, Paar (2006), Lemke-Rust, Paar (2007), Standaert, Koeune, Schindler (2009, simulation studies)
- Target: block ciphers
- Similarities with template attacks
 - uses information from several time instants
 $t_1 < t_2 < \dots < t_m$
 - interprets measurement values as values that are assumed by random variables

The stochastic approach (II)

The stochastic approach **combines**

- **engineers' expertise**

- Question: Which properties of the implementation / hardware may have significant impact on the side channel leakage? (**qualitative assessment**)

- **with advanced stochastic methods**

- Goal: exploit the available information in an optimal way

The stochastic model (basic variant)

Target: block cipher (e.g. AES), no masking

$x \in \{0,1\}^p$ (known) part of the plaintext or ciphertext (AES: $p = 8$)

$k \in \{0,1\}^s$ subkey (AES: $s = 8$)

$t \in \{t_1, t_2, \dots, t_m\}$ time instant

$$I_t(x;k) = h_t(x;k) + R_t$$

Random variable
(depends on x and k)

Deterministic part
(depends on x and k)

Random variable
 $E(R_t) = 0$

quantifies the
“randomness” of the
leakage at time t

noise

The stochastic model (considers masking)

Target: block cipher (e.g. AES)

$x \in \{0,1\}^p$ (known) part of the plaintext or ciphertext

$z \in M$ **masking value**

$k \in \{0,1\}^s$ subkey

$t \in \{t_1, t_2, \dots, t_m\}$ time instant

$$I_t(x, z; k) = h_t(x, z; k) + R_t$$

Random variable
(depends on x, z, k)

**Quantifies the
“randomness of the
leakage at time t ”**

deterministic part
(depends on x, z, k)

Random variable
 $E(R_t) = 0$

noise

Remark

- Note:
 - The functions $\mathbf{h}_{t_1}(\cdot, \cdot; \cdot), \mathbf{h}_{t_2}(\cdot, \cdot; \cdot), \dots, \mathbf{h}_{t_m}(\cdot, \cdot; \cdot)$ and
 - the probability distribution of the random vector $(\mathbf{R}_{t_1}, \mathbf{R}_{t_2}, \dots, \mathbf{R}_{t_m})$ („noise“)

are unknown.

- Profiling: The functions and the probability distributions are estimated on basis of measurements at an identical training device.

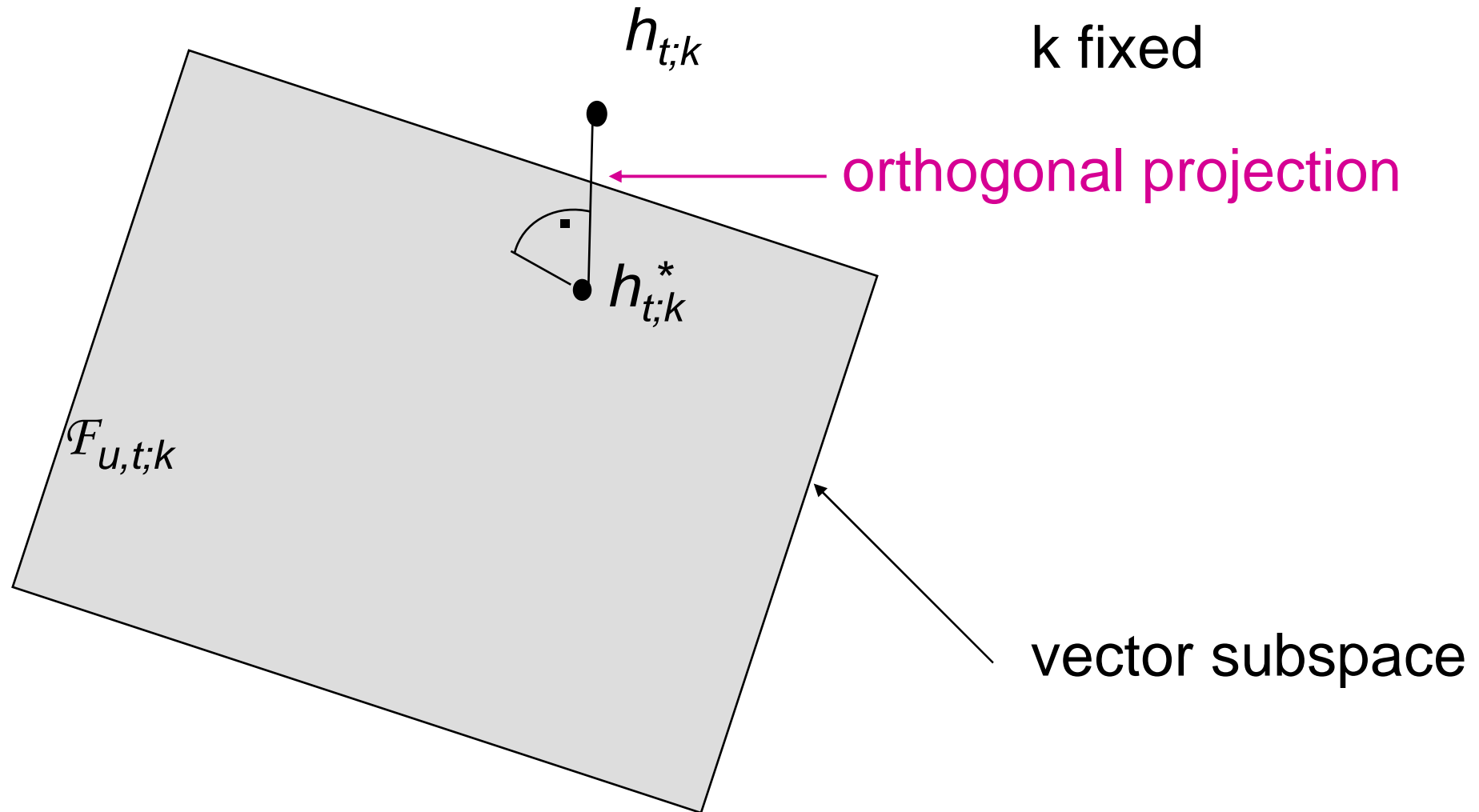
Profiling, Step 1: Naive Approach

- Estimate $h_t(x,z;k) = E(I_t(x,z;k))$
independently for each triplet
 $(x,z;k) \in \{0,1\}^p \times M \times \{0,1\}^s$
(\rightarrow template attack)
- Disadvantage: requires
 $2^{p+s}|M|$ measurement series
 \rightarrow gigantic number of measurements (= power traces), especially for strong implementations
(some reduction for chosen input attacks)

Much better ... (central idea)

- Fix a subkey $k \in \{0,1\}^s$.
- Interpret the unknown function $h_{t;k} : \{0,1\}^p \times M \times \{k\} \rightarrow \mathbb{R}$, $h_{t;k}(x,z;k) := h_t(x,z,k)$ as an element of a $2^p |M|$ -dimensional real vector space \mathcal{F} .
- Idea: approximate $h_{t;k}$ by its image $h_{t;k}^*$ under an orthogonal projection on a suitably selected low-dimensional vector subspace $\mathcal{F}_{u,t;k}$

Geometric visualisation



The vector subspace $\mathcal{F}_{u,t;k}$

The u -dimensional vector subspace

$$\mathcal{F}_{u,t;k} := \{h' : \{0,1\}^p \times M \times \{k\} \rightarrow \mathbb{R} \mid \sum_{j=0}^{u-1} \beta'_{j,t;k} g_{j,t;k} \text{ mit } \beta'_{j,t;k} \in \mathbb{R}\}$$

is spanned by u linear independent vectors (functions)

$$g_{j,t;k} : \{0,1\}^p \times M \times \{k\} \rightarrow \mathbb{R} \quad 0 \leq j \leq u-1$$

The image $h^*_{t,k}$ is the best approximator of h_t in $\mathcal{F}_{u,t;k}$ (= closest element in $\mathcal{F}_{u,t;k}$).

Main Theorem

Theorem: For any fixed subkey k the image $h_{t;k}^*$ of $h_{t;k}$ under the orthogonal projection meets the following **minimum property**:

For **random plaintext X** the mean value

$$E \left(\left(I_t(X,Z,k) - h'(X,Z,k) \right)^2 \right)$$

attains its minimum on $\mathcal{F}_{u,t;k}$ at $h' = h_{t;k}^*$.

Consequences

It is possible to determine the image $h_{t,k}^* \in \mathcal{F}_{u,t;k}$
without knowledge of the pre-image $h_{t;k}$!!

The estimation of $h_{t,k}^*$ is completely moved to the low-dimensional subspace $\mathcal{F}_{u,t;k}$.

This property reduces the number of profiling measurements to a small fraction.

Of course, the basis $g_{0,t;k}, \dots, g_{(u-1),t;k}$ of the vector subspace $\mathcal{F}_{u,t;k}$ should be selected under consideration of the attacked device (\rightarrow engineer's expertise)

Example: AES (no masking / CHES 2005) (I)

□ t_1, t_2, \dots, t_m : time instants after the S- box evaluation

□ Reasonable **candidates** for the functions $g_{j,t;k}(\cdot, k)$:

$$g_{0,t;k}(x;k) = 1$$

$$g_{j,t;k}(x;k) = j^{\text{th}} \text{ bit of } S(x \oplus k) \quad \text{for } 1 \leq j \leq 8$$

....

interpreted as a real-valued function $\{0,1\}^8 \rightarrow \mathbb{R}$

$$\mathcal{F}_{9,t;k} = \langle g_{0,t;k}, g_{1,t;k}, \dots, g_{8,t;k} \rangle$$

vector subspace generated by $g_{0,t;k}, g_{1,t;k}, \dots, g_{8,t;k}$

Example: AES (no masking / CHES 2005) (II)

Note: $\dim(\mathcal{F}_{9,t;k}) = 9$ but $\dim(\mathcal{F}) = 256$

no pre-information on h_t

- The vector basis may be extended, e.g. to capture crossover effects:

$$g_{8+j,t;k}(x,k) = g_{j,t;k}(x,k) g_{j+1,t;k}(x,k) \quad \text{for } 1 \leq j \leq 7$$

→ 16-dimensional vector subspace $\mathcal{F}_{16,t;k}$

Example AES (masked implementation)

- 8-bit bus implementation
- $t \in \{t_1, \dots, t_m\}$: instants before the S-box evaluation
- Masking: $x \rightarrow (x \oplus z) \rightarrow (x \oplus z \oplus k) \rightarrow \dots$
- Plausible candidates for the basis (depending on t)

$$g_{0,t;k}(x,z,k) = 1$$

$$g_{j,t;k}(x,z,k) = j^{\text{th}} \text{ bit of } (x \oplus z \oplus k) \quad \text{für } 1 \leq j \leq 8$$

....

Interpreted as a real-valued function $\{0,1\}^{16} \rightarrow \mathbb{R}$

Here: $\dim(\mathcal{F}_{9,t;k}) = 9$ but $\dim(\mathcal{F}) = 2^{16}$

Profiling, Step 1: Approximation of the Deterministic Part

- **Task:** Let $t \in \{t_1, \dots, t_m\}$. For each admissible subkey k estimate the coefficients $\beta_{0,t;k}^*, \dots, \beta_{(u-1),t;k}^*$ of the best approximator $h_{t;k}^*$ of $h_{t;k}$ with respect to the basis $g_{0,t;k}, \dots, g_{(u-1),t;k}$
- **Procedure:**
 1. perform N_1 measurements (i.e. observe N_1 encryptions) at the training device
 2. calculate the least-square estimate
- **Note:** This procedure may be performed separately for all $t \in \{t_1, \dots, t_m\}$

Profiling, Step 2: Modelling the noise

- Assumption: The random vector $(R_{t_1}, \dots, R_{t_m})$ is multivariate normally distributed with **covariance matrix C**
- Note: h_{t_1}, \dots, h_{t_m} and C yield the **parameter-dependent densities $f_{x,z;k}(\cdot)$** for $(I_{t_1}(x,z,k), \dots, I_{t_m}(x,z,k))$.
- **Profiling, Step 2:**
 1. Perform N_2 new measurements (i.e., observe N_2 further encryptions at the instants t_1, \dots, t_m)
 2. Determine **estimates** for \tilde{C} and $\tilde{f}_{x,z;k}(\cdot)$ for C and $f_{x,z;k}(\cdot)$

Attacking phase

- Conduct N_3 measurements at the target device
- Decide for that subkey k that maximizes the term

$$\prod_{j=1}^{N_3} \sum_{z_j \in M} \Pr(Z_j = z_j) \tilde{f}_{x_j, z_j; k}(i_j)$$

(maximum likelihood estimator)

Empirical probabilities for the correctness of the rank 1-candidate

- Reference: Schindler, Lemke, Paar (CHES 2005)
- For all instants t the 9-dimensional vector subspace $\mathcal{F}_{9;t} = \mathcal{F}_9 := \langle 1, j^{\text{th}} \text{ bit of } S(x \oplus k) \text{ for } 1 \leq j \leq 8 \rangle$ was used

N_3	DPA (HW model)	Stochastic approach ($N_1=1000$) $m=7$ ($N_2=1000$)	Stochastic approach ($N_1=1000$) $m=21$ ($N_2=5000$)
5	0.82 %	36.30 %	41.43 %
7	1.31 %	61.12 %	68.34 %
10	2.74 %	84.12 %	90.17 %
15	6.04 %	97.97 %	99.25 %
20	9.70 %	99.85 %	99.96 %
30	19.67 %	99.99 %	> 99.99 %

Comparison with template attacks (no masking, empirical results)

- ❑ Gierlichs, Lemke, Paar (2006):
Exemplary implementation: Even a reduction of the profiling measurements to 2% (relative to a template attack) preserved acceptable attacking efficiency.
- ❑ Standaert, Koeune, Schindler (2009)
Simulation studies: The stochastic approach required only 4% of the profiling measurements of template attacks with comparable attacking efficiency.

The degree of the advantage depends on the concrete implementation.

Comparison with template attacks (masking, empirical results)

- ❑ K. Lemke-Rust verified the applicability of the stochastic approach in presence of masking by many experiments.
- ❑ For masked implementations (relative to template attacks) the advantage in profiling efficiency is at least one order of magnitude larger than for implementations without masking.
- ❑ Example: AES (masked implementation)
template attacks:
 - profiling: $256 * |M| * 256$ measurement series
(reduction for chosen input attacks)
stochastic approach:
 - profiling: $256 + 1$ measurement series

Constructiveness of the stochastic approach

- If the absolute value of the coefficient $\beta_{j,t;k}^*$ is large, the „direction“ of the basis vector $g_{j,t;k}$ has significant impact on the subkey-dependent part of the leakage $h_{t;k}$ (\rightarrow quantitative description of the weakness)

This property can be used to support aimed (re-)design.

Final Remarks

The stochastic approach has several interesting properties. It

- ❑ combines **engineers' expertise** (→ selection of a suitable vector subspace $\mathcal{F}_{u,t;k}$) with **stochastic methods**
- ❑ can principally be applied to any masking scheme
- ❑ profiling: by order(s) of magnitude more efficient than for template attacks
- ❑ attacking efficiency: \leq template attacks (depends on the choice of $\mathcal{F}_{u,t;k}$)
- ❑ identifies und quantifies properties / weaknesses that have significant influence on the side-channel leakage
- ❑ can be used to support aimed design / redesign

Contact

Federal Office for Information Security
(BSI)



Werner Schindler
Godesberger Allee 185-189
53175 Bonn

Tel: +49 (0)22899 - 9582-5652
Fax: +49 (0)22899 - 10-9582-5652

Werner.Schindler@bsi.bund.de
www.bsi.bund.de
www.bsi-fuer-buerger.de