



Security evaluation of a BMOS (Biometric Match On Smartcard)

Presented by Taoufik Chouta





Plan

I – Categories of biometric authentication system

II – What is a *BMOS* system ? And why ?

III - Fingerprint features levels

IV – A Verification algorithm (algorithmic adaptation)

V – A *CPA* approach

VI - Conclusion

Categories of biometric authentication system

- *Identification*: identify biometric traits in a database => 1:n comparisons.
- *Verification*: confirming the identity of an individual => 1:1 comparison.

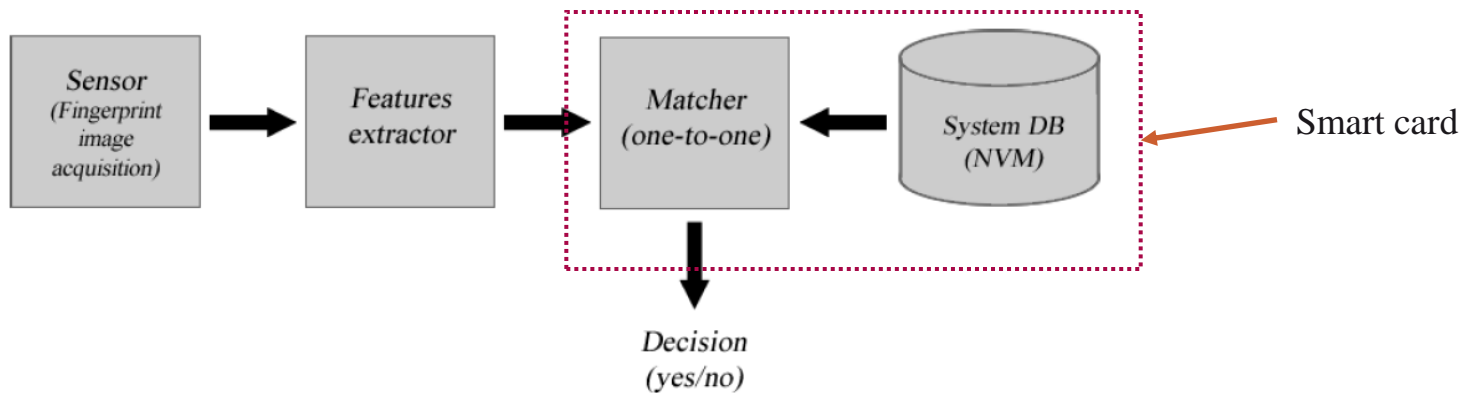


Examples of application domain

Advantages: Increasing security level by Substituting the PIN by a biometric trait

What is a BMOS system ? And why?

BMOS: Biometric Match On Smart card (matching only).



Biometric authentication system with four main modules

Advantage:

- 1- Verification inside the card, sensitive data kept secret.
- 2- Only decision is communicated (avoid direct Hill Climbing attacks [2])

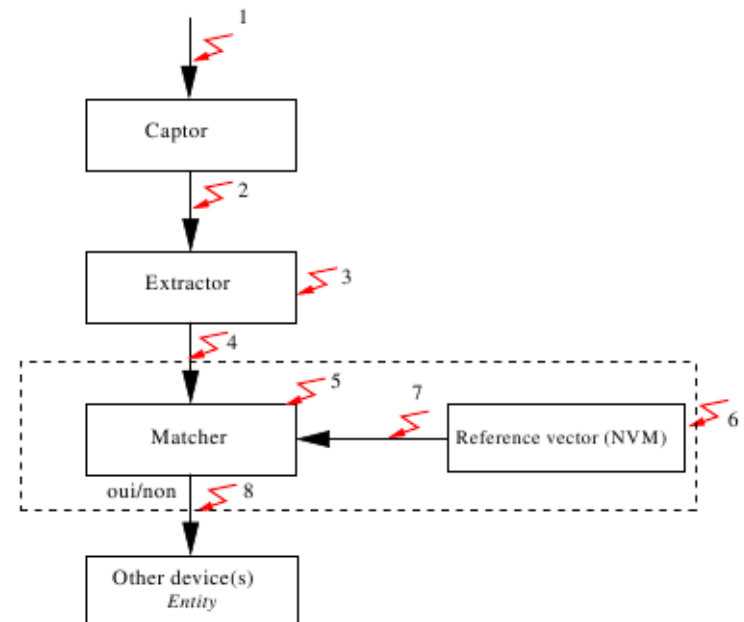
Drawbacks:

- Limitation of available resources
- Small RAM memory.
 - Internal clock (24Mhz)
 - Low calculation magnitude of the CPU

Potential attacks on generic biometric system

Potential attacks:

1. Using false finger.
2. Biasing the captor + Hill Climbing.
3. Forcing the extractor.
4. Intercepting and modifying the input vector.
5. *Spying or forcing the comparator computation.*
6. Tampering with the reference set.
7. Intercepting the reference set.
8. Overriding the final decision.



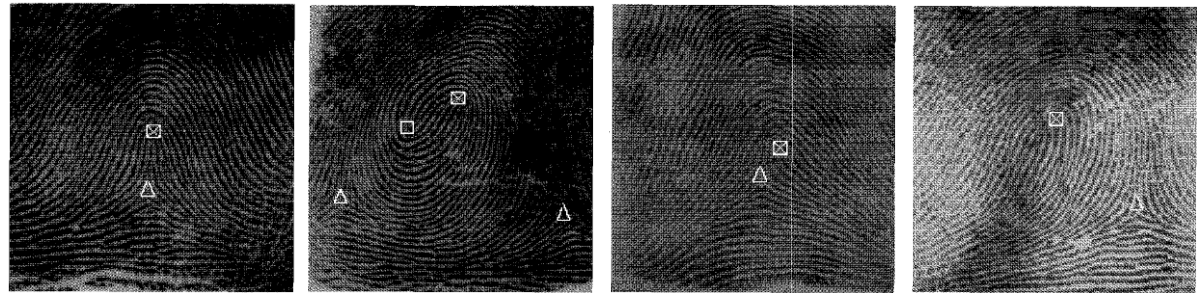
Potential attacks on biometric system

Attacks concerning smart card are surrounded: 4,5,6,7,8.

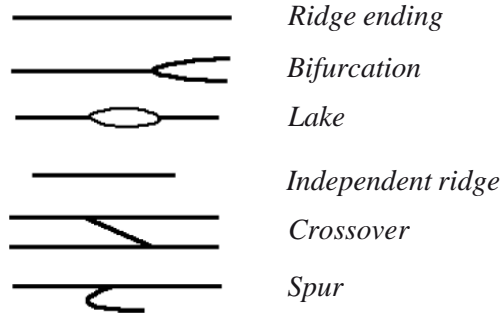
Fingerprint features levels (the secret data)

Level 1:

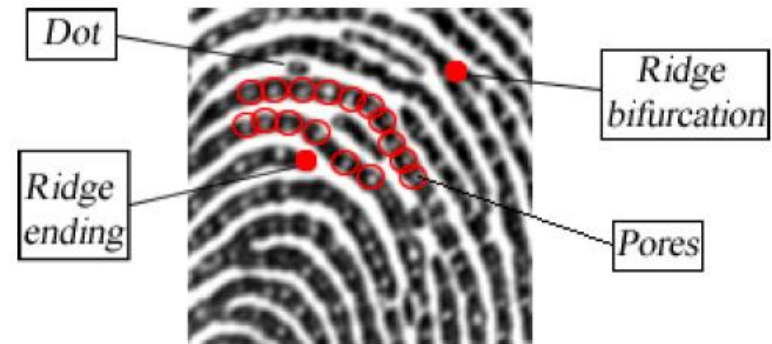
Core and delta positions.
(Global ridge shape)



Level 2: Minutiae (local ridge shape).

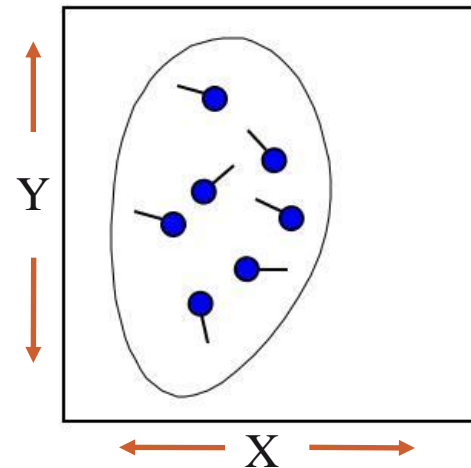
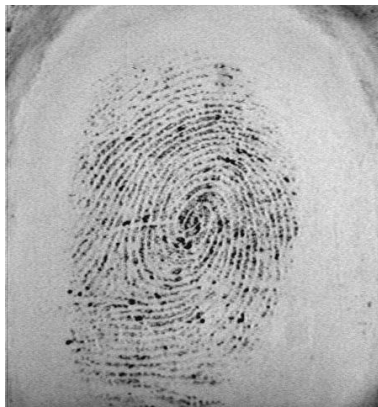
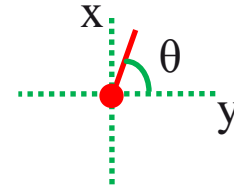


Level 3: High definition details: pores, dots...



Fingerprint features levels (the secret data)

Compact version of the ISO standard 19794-2:
ridge ending & bifurcation minutiae (θ, x, y)



- Minutiae (θ, X, Y) coordinates are coded on (6,8,8) bits.
⇒ 256x256 image grid.
⇒ 64 possible orientations.

The studied verification algorithm

- The fingerprint verification problem can be presented as a point pattern matching.

Difficulties:

- 1- Sets are not sorted (depends on the extractor).
- 2- False minutiae (image quality).
- 3- Deformed minutiae (skin elasticity).
- 4- Sets with different cardinals (finger position).
- 5- No common landmark (core or delta)



Bad quality Images

Unlike cryptography there is no standard biometric verification algorithm !!

The studied verification algorithm

Two steps algorithm [3]:

1- Registration :

From two minutiae points sets, calculate best $\{\Delta\theta, \Delta x, \Delta y\}$ of affine transformation overlapping both sets (linear model).

$$T_{\Delta\theta, \Delta x, \Delta y} = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} \Delta x \\ \Delta y \end{bmatrix}$$

The affine transformation

Constraints for smart card implementations:

- Verification in less than 0.5 second.
- Low performances deterioration.
- Limited resources.

2- Pairing:

- Apply the found transformation.
- Find nearest minutiae point in both sets and calculate a matching score.



Finger A

Finger B

Overlapped fingerprints

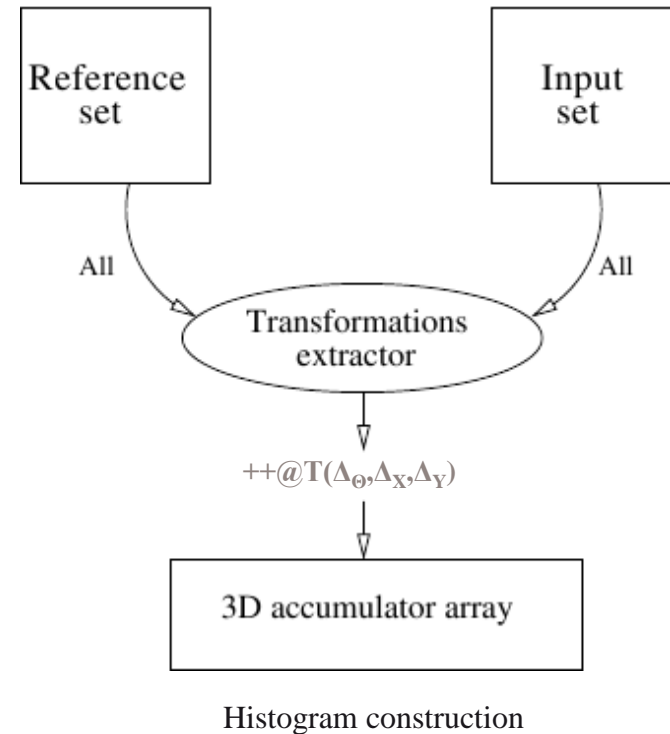
The studied verification algorithm

Registration :

Transformation histogram construction:

1. Calculate Δ_{θ}
2. Apply rotation on input minutiae.
3. Calculate Δ_X, Δ_Y
4. Increment @ $(\Delta_{\theta}, \Delta_X, \Delta_Y)$.

- Statistically if the same parameters appears many times, they are likely to be the most appropriate ones for the analysis.

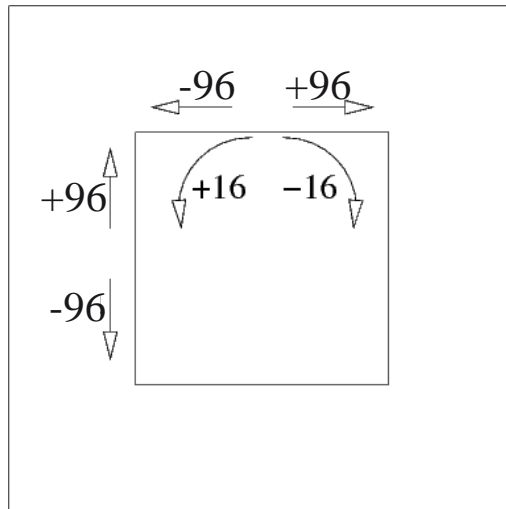


The studied verification algorithm

Histogram memory requirement:

$[-96, 96[^2 * [-16, 16[$ for translations and rotation respectively.

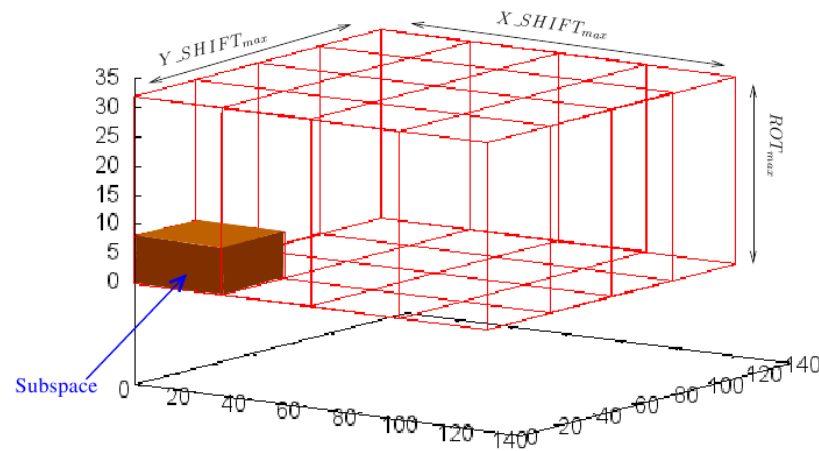
- ⇒ Accumulator size 1.18MB! (...*On smart card??!*)
- ⇒ How to reduce the required memory?
- ⇒ What is the impact on the algorithm performances?



Rotation, translation inside
an image grid

The algorithm adaptation

Transformation Subspaces:



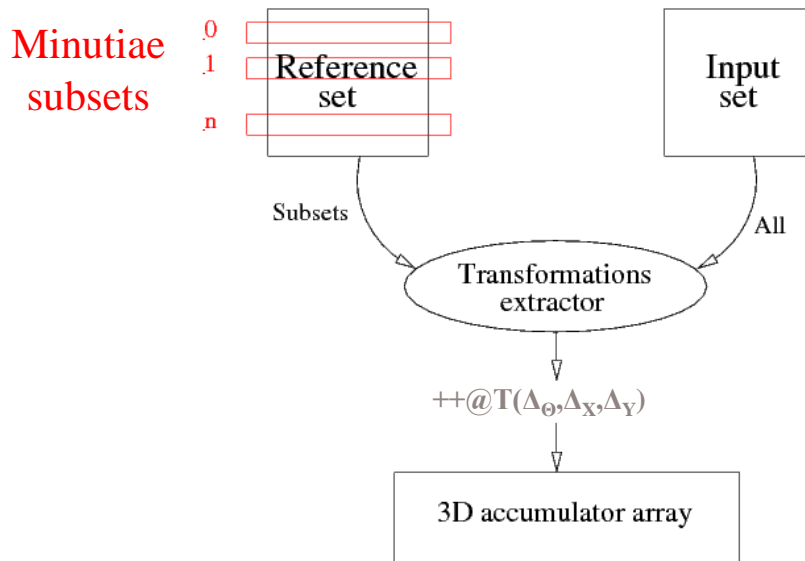
Transformation space fragmentation

- Fragmentation of the transformation histogram space to many subspaces.
- A registration is done for each subspace.
 - ⇒ Required memory is relative to subspace dimension.
 - ⇒ Whole transformation space is parsed (no performance loss).
 - ⇒ Registration is repeated many times.

The algorithm adaptation

Transformation Subspaces:

Optimization n°1: Targeting a subset of minutiae involved in each subspace registration.



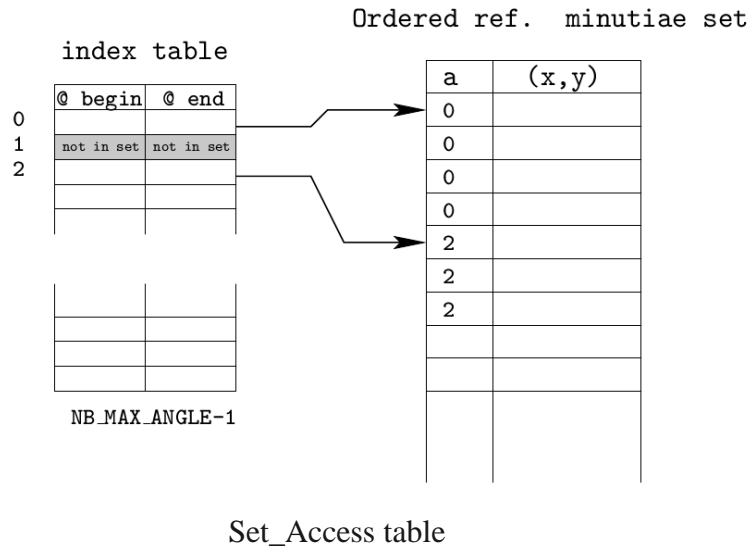
⇒ For each minutiae in the input set, find reference minutiae with high probability to lead to a transformation accepted by the actual processed subspace.

The algorithm adaptation

Transformation Subspaces:

Optimization n°1: The Set_Access Table

- Sort reference minutiae in an increasing angle order.
- Use set_access table pointing to the first and last minutiae with a particular orientation angle.
- Sorting reference minutiae is done once and off-line.

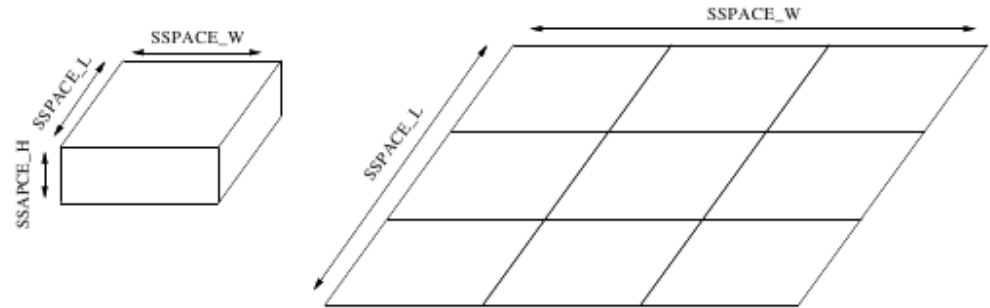


The algorithm adaptation

Transformation Subspaces:

Optimization n^2 : Subspace dimension strategy

- Increasing **translation** dimensions will decrease rejected transformations.
- Decreasing **rotation** dimension will not affect transformation acceptance by actual subspace.
- Same memory can represent many subspace dimensions

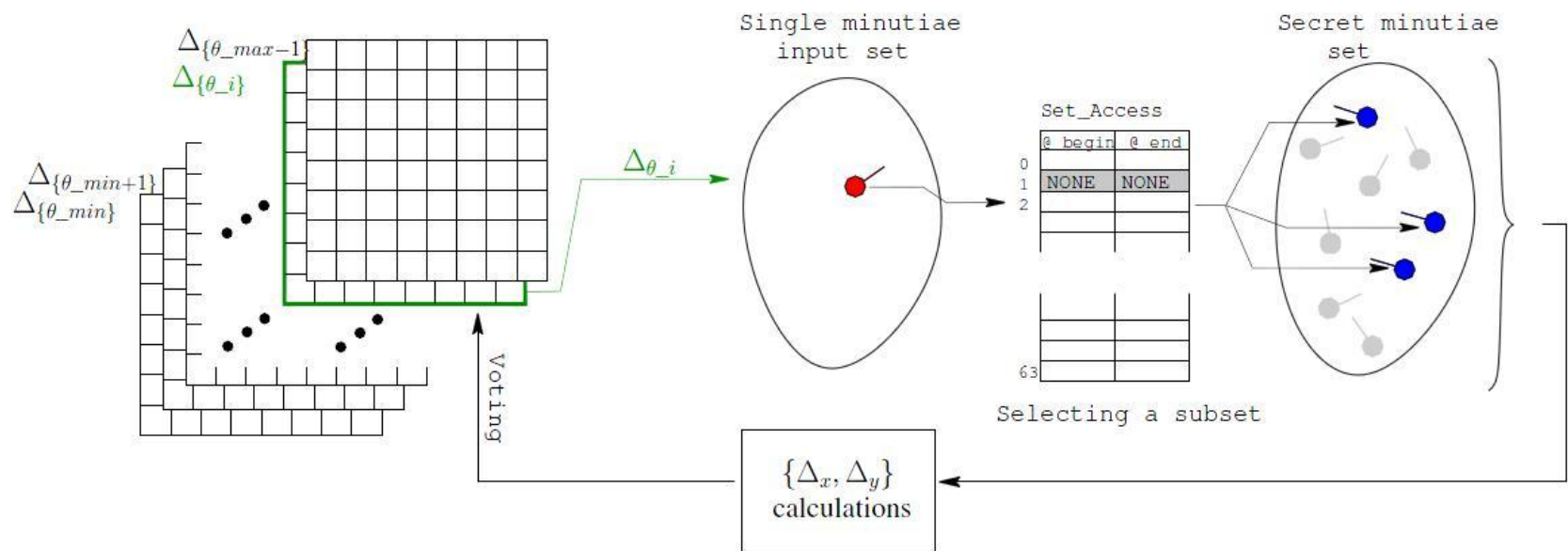


Same memory space representing
two subspace dimensions

⇒ Less transformations are rejected due to $\Delta x, \Delta y$ out of the subspace borders

The algorithm adaptation

Histogram subspace computation:



Histogram subspaces construction using a memory mapping array

A CPA approach

CPA attack on the first subspace:

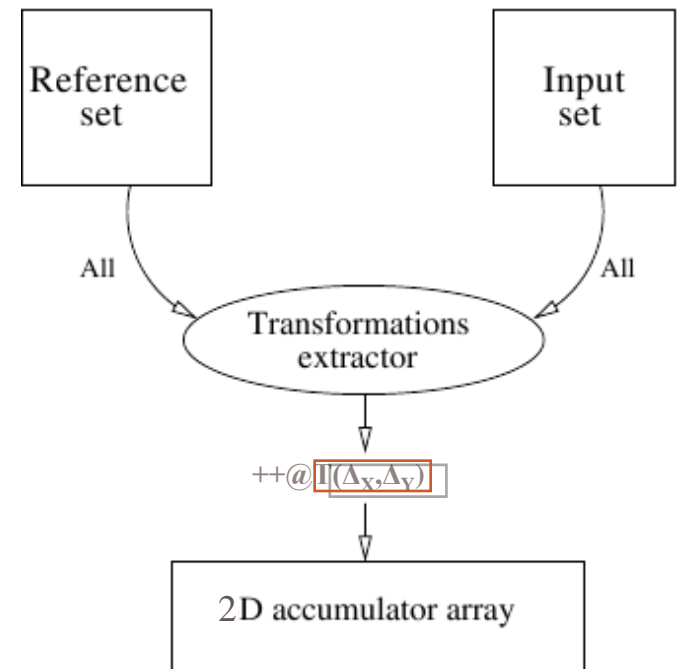
- By analogy to a ciphering algorithm
The key is : a secret minutiae coordinates.
The message is: input minutiae coordinates.
Attacked registers: Δx and Δy registers.

⇒ The algorithm adaptation allows to target specific minRef. θ . Thus we assume θ is known.

⇒ Computing the leakage hypothesis

⇒ Hypothesis are done on $(X, Y) = (2^{16})$.

Remark: with a straightforward implementation hypothesis space will be composed from (2^{22}) minutia.

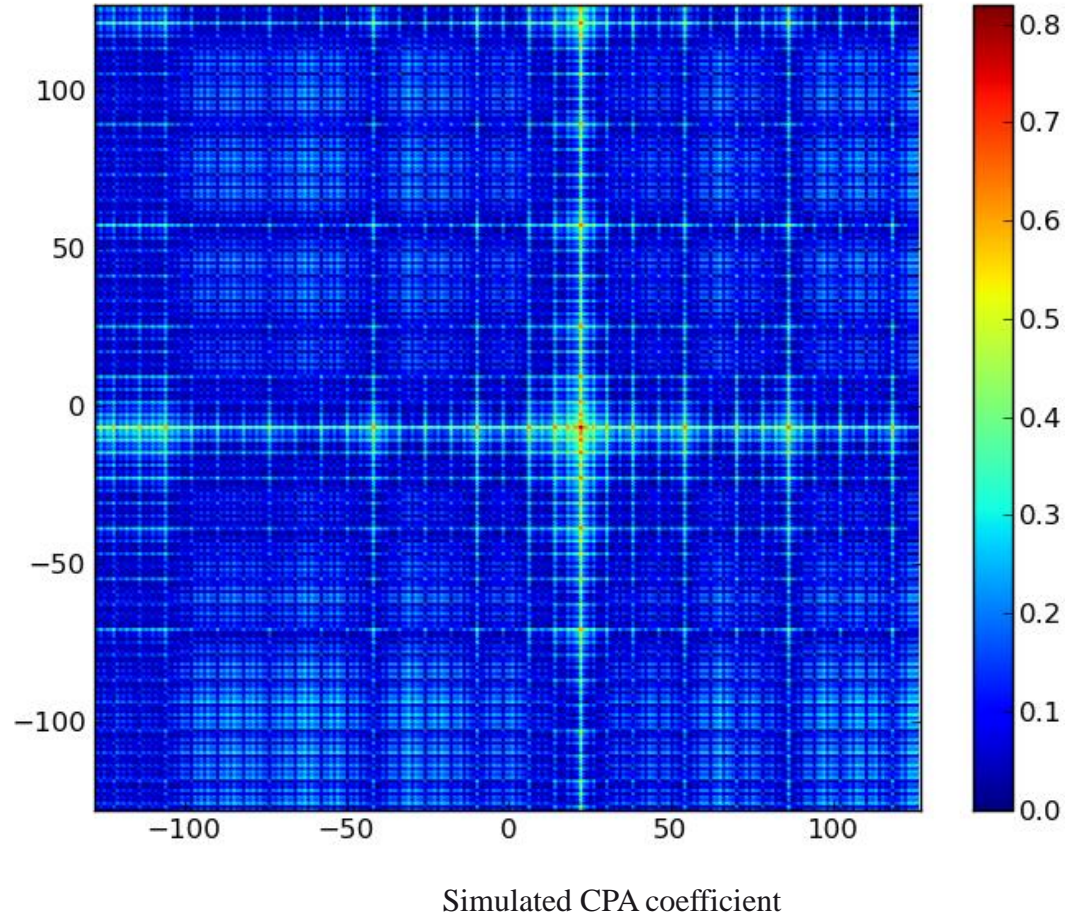


Histogram construction

A CPA approach (Simulated attack)

Example of simulated results :

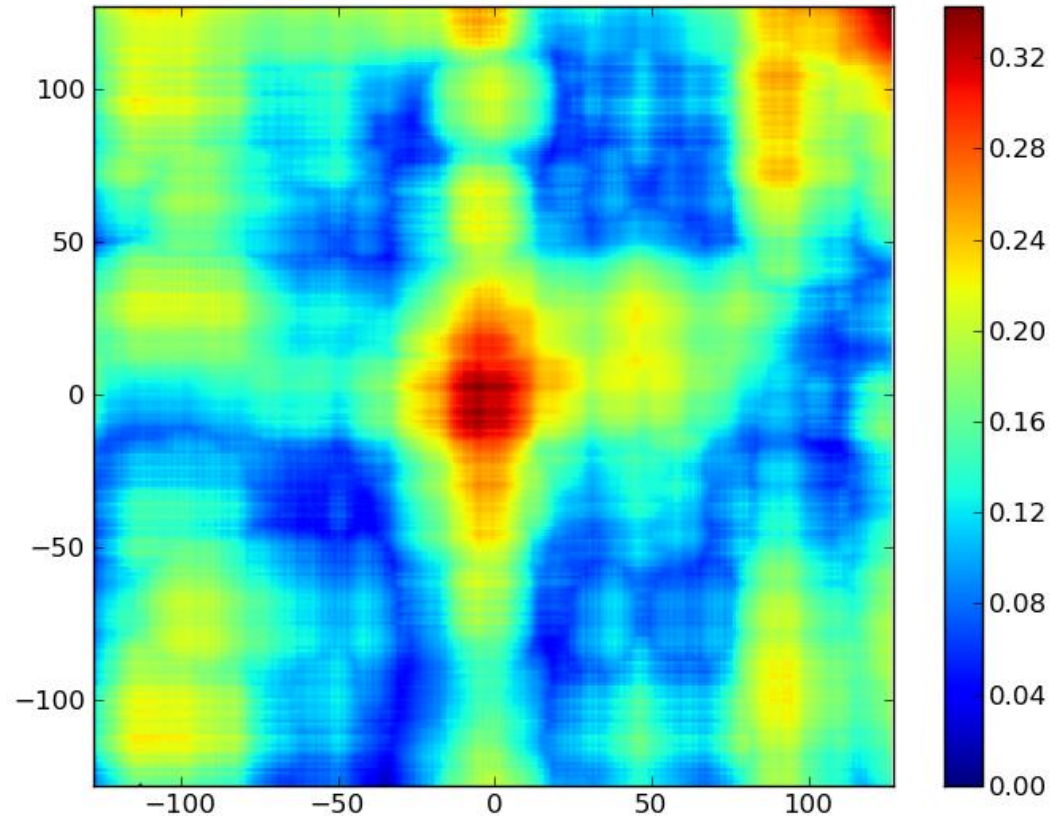
- $\text{Min}_{\text{secret}} = (21, 22, -7)$
 - Nbr traces = 1000
 - SNR = 2.5
 - Remark: high correlation on :
 $\text{Min}_{\text{hyp}} = (21, 22, y)$ and
 $\text{Min}_{\text{hyp}} = (21, x, -7)$
- => The rotation during the first registration round is near to zero.



A CPA approach (Real attack)

Results of real attack :

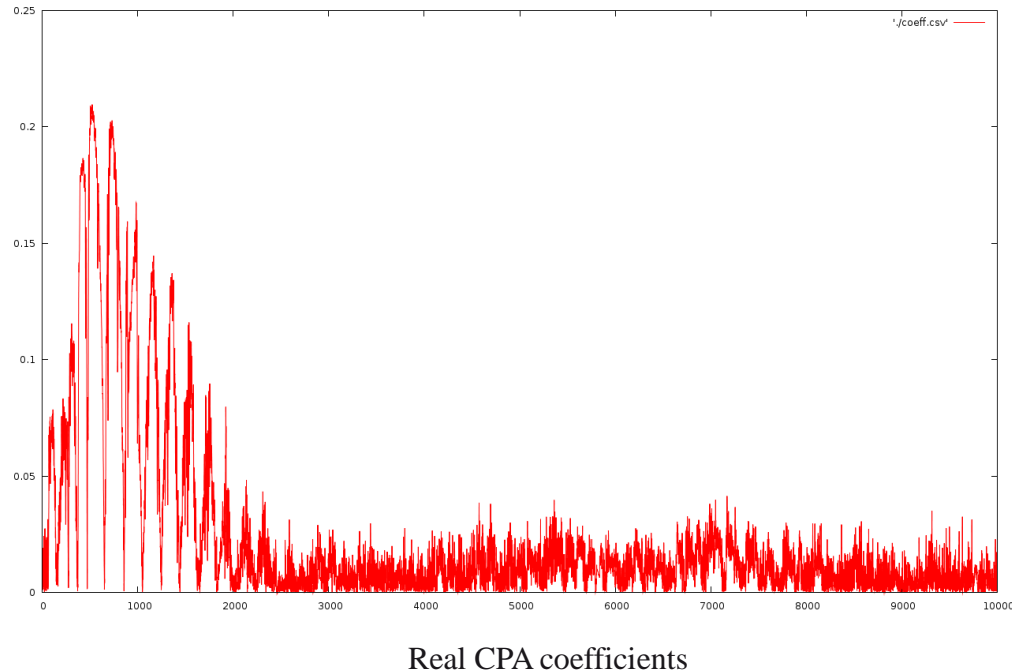
- $\text{Min}_{\text{True}} = (21, 22, -7)$
- Nbr traces = 30K
- Remark: high correlation on false hypothesis (0.34)



Results of real CPA

A CPA approach (Real attack)

Results of real attack :



- What gives multiple correlation spikes ...?
=> Data loading ?
=> Attacked registers are used at next processing entities?



Conclusion & Perspectives

- **Conclusion:**
 - Algorithm adaptation of a BMOS algorithm to limited resources systems.
 - Potential side channel attack on the registration phase.

- **Perspectives:** evaluating the efficiency of the following countermeasures:
 - Randomizing subspaces sequence.
 - Masking by using false minutiae.
 - Transforming the input vector before computation.
 - Randomizing the input set as well.



Questions ?

Thank you for your
attention



References

[1] “Spotlight on Biometrics[online],” <http://www.unisyssecurityindex.com>.

[2] Hill-Climbing and Brute-Force Attacks on Biometric Systems: A Case Study in Match-on-Card Fingerprint Verification, oct. 2006.

[3] N. K. Ratha, K. Karu, S. Chen, and A. K. Jain, “A real-time matching system for large fingerprint databases,” *IEEE Trans. Pattern Anal. Mach. Intell.*, vol. 18, no. 8, pp. 799–813, 1996.

Annex: Biometric traits

Biometric technologies evaluation [1]

Effort: the end user required effort.

Intrusiveness: end user acceptance of the biometrical technology.

Cost: technology cost, (reader, scanner...).

Accuracy: discrimination level the biometric trait.

