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On the Optimality of Mutual Information Analysis for Discrete Leakages

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Outline

Introduction

On Optimality of MIA

- Notations and Assumptions

- Mathematical Derivations

An Example where MIA Outperforms CPA

- Pedagogical Case-Study

Implementation Issues

- On Binning Size

- Fast Computation of MIA



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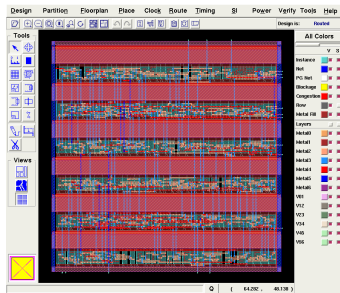


Research thread: “*Distinguishing distinguishers*”

- CHES 2014: known model + large Gaussian noise
⇒ **CPA is optimal**
- ASICRYPT 2014: idem with masking
⇒ **HO-CPA is optimal**
- CRYPTARCHI 2015: unknown model
⇒ **MIA is optimal**

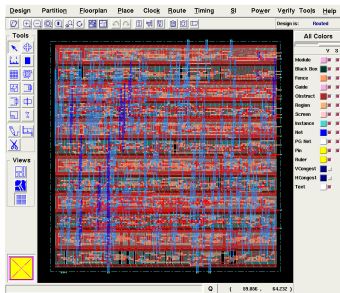
Motivations

1. How to attack when
 - no leakage model is available?
 - no profiling is possible?(e.g., balanced dual-rail circuits)



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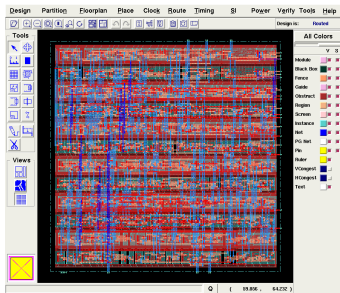
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→ Mutual Information Analysis (MIA) [Gierlichs et al., CHES 2008]



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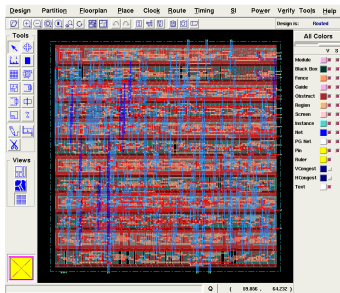
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(e.g., balanced dual-rail circuits)

→ Mutual Information Analysis (MIA) [Gierlichs et al., CHES 2008]

2. Is it possible for MIA to be:

- Optimal?
- Effective?
- Efficient?





Results

We show that:

- MIA is “optimal” in that it is equivalent to a “universal” maximum likelihood (U-ML)
- MIA can even outperform CPA
- the computational complexity of MIA can be significantly reduced



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Leakage model

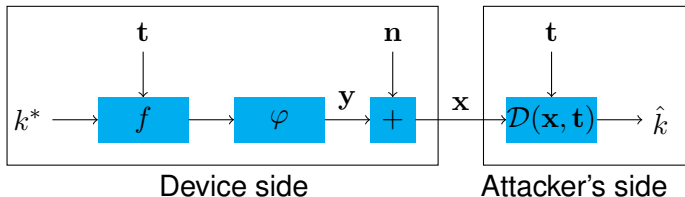
Assumptions:

- secret key k^* : deterministic but unknown
- uniformly distributed text bytes $\mathbf{t} = (t_1, \dots, t_m)$: random but known
- m i.i.d. noisy measurements $\mathbf{x} = (x_1, \dots, x_m)$

$$\mathbf{x} = \mathbf{y}(k^*) + \mathbf{n}$$

- leakage model:

$$\mathbf{y}(k) = \varphi(f(k, \mathbf{t}))$$



Markov Chain Property

Markov Condition

The leakage \mathbf{x} depends on the secret key k^* only through the computed model $\mathbf{y}(k^*) = \varphi(f(k^*, \mathbf{t}))$

Thus the *conditional distribution* $\mathbb{P}(\mathbf{x}|\mathbf{y})$ depends on the key only through the value of \mathbf{y} .

Example

- $x_i = w_H(k^* \oplus t_i) + n_i$, where w_H is the Hamming weight
- $x_i = \varphi(S(k^* \oplus t_i)) + n_i$, where S is a substitution box

Empirical Distribution (Histogram)

Assumptions

Leakage is discrete (or discretized *via* binning).

Counting occurrences of each value of x and y gives the estimate:

$$\tilde{\mathbb{P}}(x|y) = \frac{\sum_{i=1}^m \mathbf{1}_{x_i=x, y_i=y}}{\sum_{i=1}^m \mathbf{1}_{y_i=y}}$$

Definition (Empirical Mutual Information)

$$\tilde{I}(X; Y) = \sum_{x \in \mathcal{X}} \sum_{y \in \mathcal{Y}} \tilde{\mathbb{P}}(x, y) \log_2 \frac{\tilde{\mathbb{P}}(x, y)}{\tilde{\mathbb{P}}(x) \tilde{\mathbb{P}}(y)}$$

Best Distinguisher

The optimal distinguisher $\mathcal{D}(\mathbf{x}, \mathbf{y})$ and associated distinguishing rule $\hat{k} = \arg \max_{k \in \mathcal{K}} \mathcal{D}(\mathbf{x}, \mathbf{y})$ maximizes success:

Definition (Average Success Rate)

$$SR = \frac{1}{2^n} \sum_{k=0}^{2^n-1} \mathbb{P}_k(\hat{k}(\mathbf{X}, \mathbf{T}) = k)$$

This is a theoretical definition since $\mathbb{P}_k(\mathbf{x}, \mathbf{t})$ is not known perfectly.

Maximum likelihood

Theorem (Optimal Distinguisher = Maximum Likelihood)

$$\mathcal{D}_{opt}(\mathbf{x}, \mathbf{t}) = \arg \max_{k \in \mathcal{K}} \mathbb{P}(\mathbf{x} | \mathbf{y})$$

Recall $\mathbf{y} = \varphi(f(k, \mathbf{t}))$ depends on the key hypothesis k .

Proved by [Heuser et al., in CHES 2014]

Optimality holds for perfectly known leakage model φ

Universal Maximum Likelihood

Universal = from the data without prior information.

Definition (Universal Maximum Likelihood)

$$\hat{k} = \arg \max_{k \in \mathcal{K}} \tilde{\mathbb{P}}(\mathbf{x}|\mathbf{y})$$

where $\tilde{\mathbb{P}}(\mathbf{x}|\mathbf{y}) = \prod_{i=1}^m \tilde{\mathbb{P}}(x_i|y_i)$

Loss in performance due to empirical probability estimation.

Universal Maximum Likelihood

Theorem (MIA = U-ML)

The universal ML key estimate is equivalent to MIA! [Gierlichs et al. CHES 2008]

$$\hat{k} = \arg \max_{k \in \mathcal{K}} \tilde{\mathbb{P}}(\mathbf{x}|\mathbf{y}) = \arg \max_{k \in \mathcal{K}} \tilde{I}(X; Y)$$

This surprising theoretical result shows that MIA is “universally” optimal.

Proof of the Theorem

Rearrange empirical probability:

$$\tilde{\mathbb{P}}(\mathbf{x}|\mathbf{y}) = \prod_{i=1}^m \tilde{\mathbb{P}}(x_i|y_i) = \prod_{x \in \mathcal{X}, y \in \mathcal{Y}} \tilde{\mathbb{P}}(x|y)^{n_{x,y}}$$

where

$$n_{x,y} = \sum_{i=1}^m \mathbf{1}_{x_i=x, y_i=y} = m\tilde{\mathbb{P}}(x, y)$$

Now take the logarithm:

$$\log \tilde{\mathbb{P}}(\mathbf{x}|\mathbf{y}) = \sum_{x \in \mathcal{X}, y \in \mathcal{Y}} m\tilde{\mathbb{P}}(x, y) \log(\tilde{\mathbb{P}}(x|y))$$

We recognize **entropy**!

$$\tilde{H}(X|Y) = - \sum_{x \in \mathcal{X}, y \in \mathcal{Y}} \tilde{\mathbb{P}}(x, y) \log(\tilde{\mathbb{P}}(x|y)) \quad / \dots$$

Proof of the Theorem (cont'd)

In other words:

$$\tilde{\mathbb{P}}(\mathbf{x}|\mathbf{y}) = 2^{-m\tilde{H}(X|Y)}$$

Thus maximizing $\tilde{\mathbb{P}}(\mathbf{x}|\mathbf{y})$ amounts to minimizing $\tilde{H}(X|Y)$, i.e., maximizing

$$\tilde{I}(X, Y) = \tilde{H}(X) - \tilde{H}(X|Y)$$

since $\tilde{H}(X)$ does not depend on k .

Conclusion:

$$\arg \max_{k \in \mathcal{K}} \tilde{\mathbb{P}}(\mathbf{x}|\mathbf{y}) = \arg \max_{k \in \mathcal{K}} \tilde{I}(X; Y)$$





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Case-Study

Consider the following leakage : $X = Y + N$ with $Y = \varphi(f(T \oplus K^*))$ where $Y = \pm 1$ and $N \sim \mathcal{U}(\pm\sigma)$ (uniformly distributed with values $\pm\sigma$).

Assumptions

- $T, K \in \mathbb{F}_2^n$
- $f : \mathbb{F}_2^n \rightarrow \mathbb{F}_2^n$ is an Sbox function applied to a xor and φ is a one-bit selection function.
- $\sigma \in \mathbb{N}$ is an integer

Example

Dynamic Voltage Scaling (DVS) used as a countermeasure.

Case-Study: Distinguisher

Theorem (Optimal Distinguisher)

One easily finds

$$\mathcal{D}_{opt}(\mathbf{x}, \mathbf{t}) = \arg \max_{k \in \mathcal{K}} \mathbb{P}(\mathbf{x}|\mathbf{y}) = \arg \max_{k \in \mathcal{K}} \frac{1}{2^m} \prod_{i=1}^m \begin{cases} 1 & \text{if } x_i - \varphi(f(t, k)) = 0 \\ 1 & \text{if } x_i - \varphi(f(t, k)) = 2\sigma \\ 0 & \text{otherwise} \end{cases}$$

To be compared to

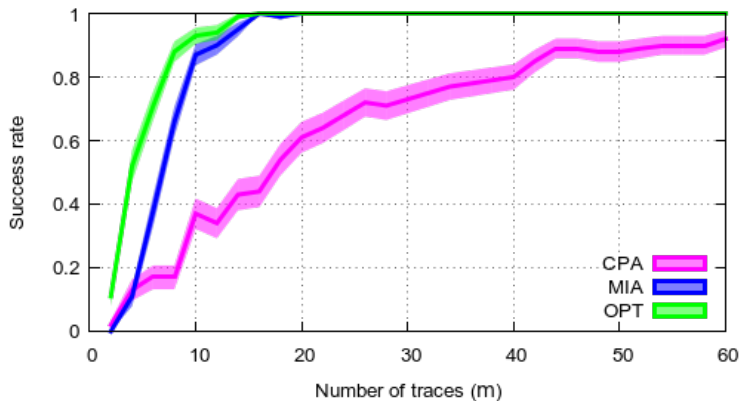
i CPA:

$$\mathcal{D}_{CPA}(\mathbf{x}, \mathbf{t}) = \arg \max_{k \in \mathcal{K}} \frac{\widetilde{\text{cov}}(X, Y)}{\tilde{\sigma}_X \tilde{\sigma}_Y}$$

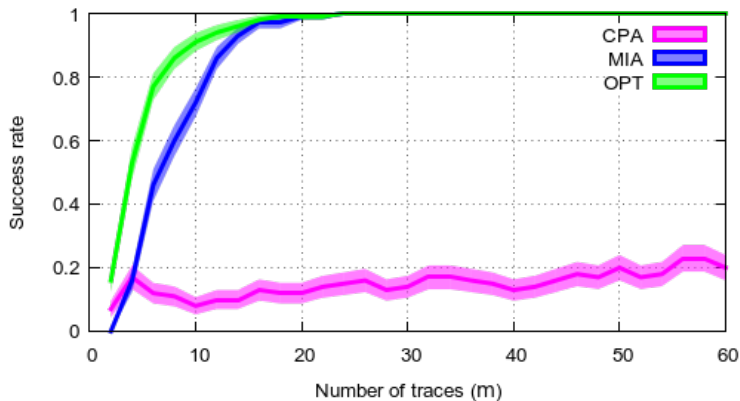
ii MIA :

$$\mathcal{D}_{MIA}(\mathbf{x}, \mathbf{t}) = \arg \max_{k \in \mathcal{K}} \tilde{I}(X, Y)$$

Results for MIA and CPA ($\sigma = 1$)



Results for MIA and CPA ($\sigma = 4$)





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Size of the Bins

Why Binning?

Due to noise, \mathbf{x} assumes real values: $p(\mathbf{x}|\mathbf{y})$ as a pdf that must be estimated using bins as $\tilde{\mathbb{P}}(\mathbf{x}|\mathbf{y})$

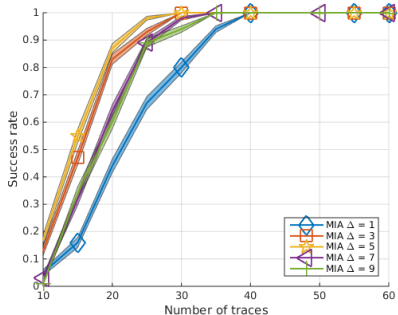
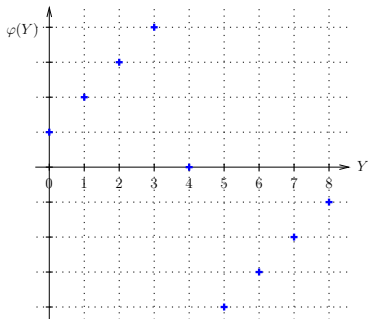
- what is the optimal size of bins?
- does it depend of the number of traces?

Leakage Example

Example

$\mathbf{y} = \varphi(f(\mathbf{y}(k^*, \mathbf{t})))$ with

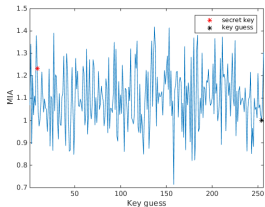
- $f(k, \mathbf{t}) = \text{Sbox}(\mathbf{t} \oplus k^*)$
- $\varphi = \psi(w_H(\bullet))$ where ψ is a non-linear bijective function s.t. $\text{Cov}(Y, \varphi(Y)) = 0$



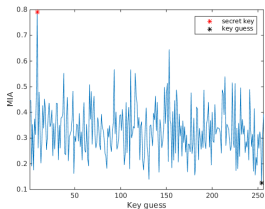
Leakage Example (cont'd)

MIA using 30 traces

$$\Delta = 1$$



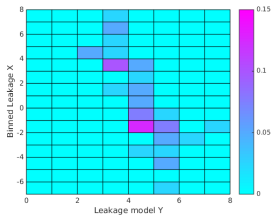
$$\Delta = 5$$



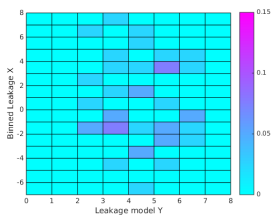
Leakage Example (cont'd)

$\Delta = 1$

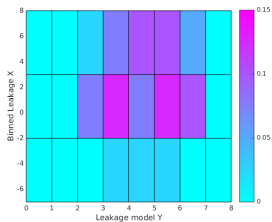
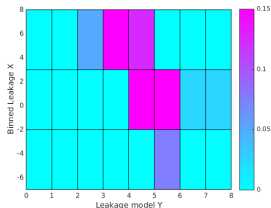
Correct key guess



False key guess



$\Delta = 5$



Fast MIA Algorithm Principle

See [Victor Lomné et al. in ASIACRYPT 2013] for CPA

Principle

The pmf is given by

$$\tilde{\mathbb{P}}(y, x) = \sum_{t|\varphi(f(t,k))=y} \tilde{\mathbb{P}}(t, x)$$

Implement this once and for all in place of empirical probability $\tilde{\mathbb{P}}(t, x)$.

Fast MIA Algorithm Flow

input : x a set of m traces which take discrete values, t a corresponding set of m plaintexts/ciphertexts

output: $(\tilde{I}(x, y(k)))_{k \in \mathcal{K}}$

// From x and t , build an hash table $PMF[t][x]$ (i.e., an histogram);

1 **for** $i \in \{1, \dots, m\}$ **do**

2 | $PMF[t_i][x_i] += 1;$

3 **end**

4 **for** $x \in \mathcal{X}$ **do**

5 | $P(x) = 0;$

// $P(x)$ holds $m\tilde{P}(x)$

6 | **for** $t \in \mathbb{F}_2^n$ **do**

7 | | $P(x) += PMF[t][x];$

8 | **end**

9 **end**

Fast MIA Algorithm Flow

```
1 for  $k \in \mathcal{K}$  do // Key enumeration
2    $\forall x \in \mathcal{X}, y \in \mathcal{Y}, P(x, y) = 0;$  //  $P(x, y)$  holds  $m\tilde{P}(x, y)$ 
3   for  $t \in \mathbb{F}_2^n$  do
4     for  $x \in \mathcal{X}$  do
5        $P(x, \varphi(f(k, t))) += \text{PMF}[t][x];$  //  $y = \varphi(f(k, t))$ 
6     end
7   end
8    $\tilde{I}(\mathbf{x}, \mathbf{y}(k)) = 0;$ 
9   for  $y \in \mathcal{Y}$  do
10     $P(y) = 0;$  //  $P(y)$  holds  $m\tilde{P}(y)$ 
11    for  $x \in \mathcal{X}$  do
12       $P(y) += P(x, y);$ 
13    end
14    for  $x \in \mathcal{X}$  do
15      if  $P(x, y) \neq 0$  then //  $P(x, y) \neq 0 \implies (P(x) \neq 0 \wedge P(y) \neq 0)$ 
16         $\tilde{I}(\mathbf{x}, \mathbf{y}(k)) += \frac{P(x, y)}{m} \log_2 \frac{mP(x, y)}{P(x)P(y)};$ 
17      end
18    end
19  end
20 end
21 return  $(\tilde{I}(\mathbf{x}, \mathbf{y}(k)))_{k \in \mathcal{K}}$ 
```


Fast MIA Algorithm Flow

```
1 for k ∈ K do // Key enumeration
2   ∀x ∈ X, y ∈ Y, P(x, y) = 0; // P(x, y) holds mP̃(x, y)
3   for t ∈ F₂ⁿ do
4     for x ∈ X do
5       P(x, φ(f(k, t))) += PMF[t][x]; // y = φ(f(k, t))
6     end
7   end
8   Ĩ(x, y(k)) = 0;
9   for y ∈ Y do
10    P(y) = 0; // P(y) holds mP̃(y)
11    for x ∈ X do
12      P(y) += P(x, y);
13    end
14    for x ∈ X do
15      if P(x, y) ≠ 0 then // P(x, y) ≠ 0 ⇒ (P(x) ≠ 0 ∧ P(y) ≠ 0)
16        Ĩ(x, y(k)) += P(x, y) log₂ P(x, y) / P(y); // no longer a mutual information, but OK...
17      end
18    end
19  end
20 end
21 return (Ĩ(x, y(k)))_{k ∈ K}
```



Conclusions

- MIA is equivalent to Universal ML
- MIA can be close to optimal
- Binning size is crucial
- Fast MIA



Thank you!

Questions?

References



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